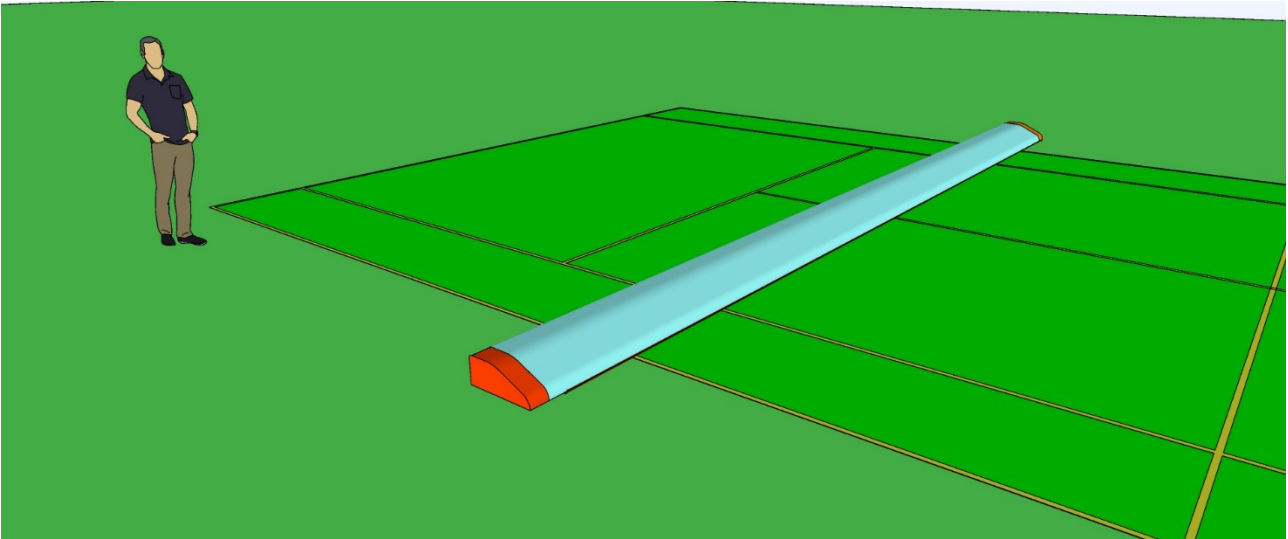


# TROBOT.LW

## Maintenance lawn court



### Lawn trimming

TroboT proceeds step by step from its Harborage till the court net. During each step TroboT stops and the grass mowers shift from one side to the other on dedicated rails trimming the lawn from one pole net to the other one. The trimmed grass is deposited in a tank where a level switch is installed.

### Line tracing

TroboT moves from its Harborage till the court net step by step. During each step TroboT stops and the line tracers shift from one side to the other on the lawn mower rails tracing the horizontal white lines. Then TroboT returns back step by step toward from its harborage tracing the vertical white lines. Each step is electronically controlled to ensure a perfect line tracing.

### Remote commands from a PC or Tablet

1. TroboT trims the lawn. It moves from its harborage till the court net and from the court net to its harborage
2. TroboT traces the white lines. It moves from its harborage till the court net and from the court net to its harborage.